**Computer Graphics** Summary, Applications, and Outlook

Matthias Teschner

#### Introduction to Computer Graphics

Rendering	Modeling	Simulation		
Homogeneous Notation				
Ray Casting	Bézier Curves	Particle Fluids		
Rasterization	Piecewise			
Phong	Polynomial Curves			

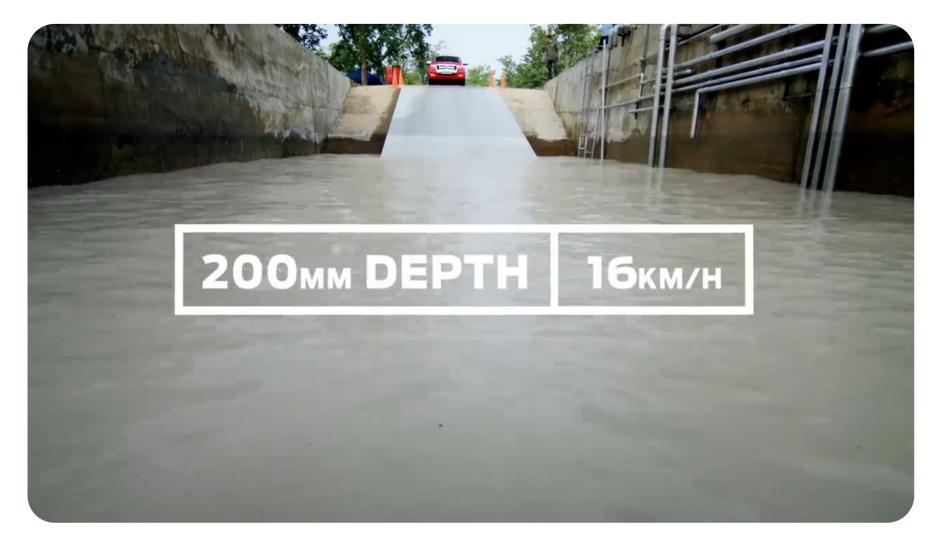
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#### *Simulations / Renderings vs. Experiments / Real-World Videos*

- Less expensive
- Faster
- More flexible
- Less dangerous

... if sufficiently accurate

### Application



The Ford Motor Company of Australia

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## Challenges

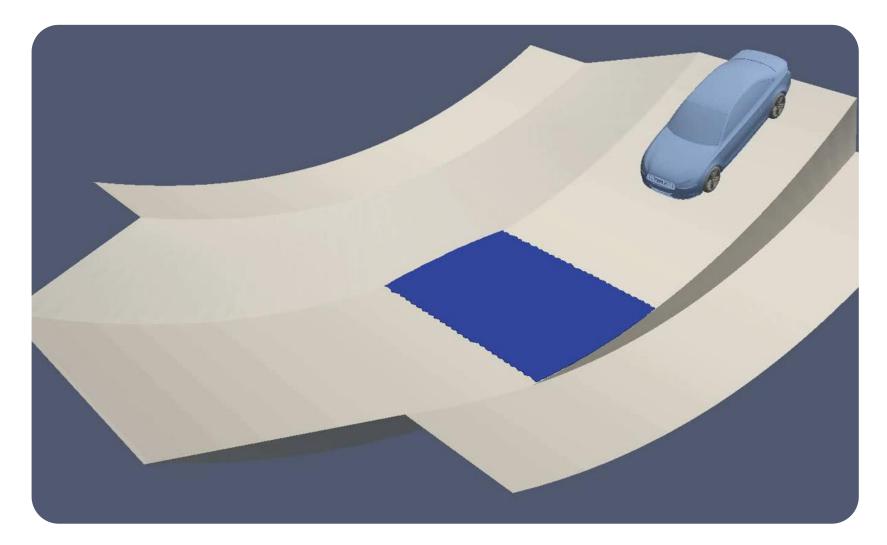
- Prototype
- Sensors
  - Wetting, pressure, volume, flow rate, pathline, ...
- Analysis
- Redesign
- Prototype





The Ford Motor Company of Australia

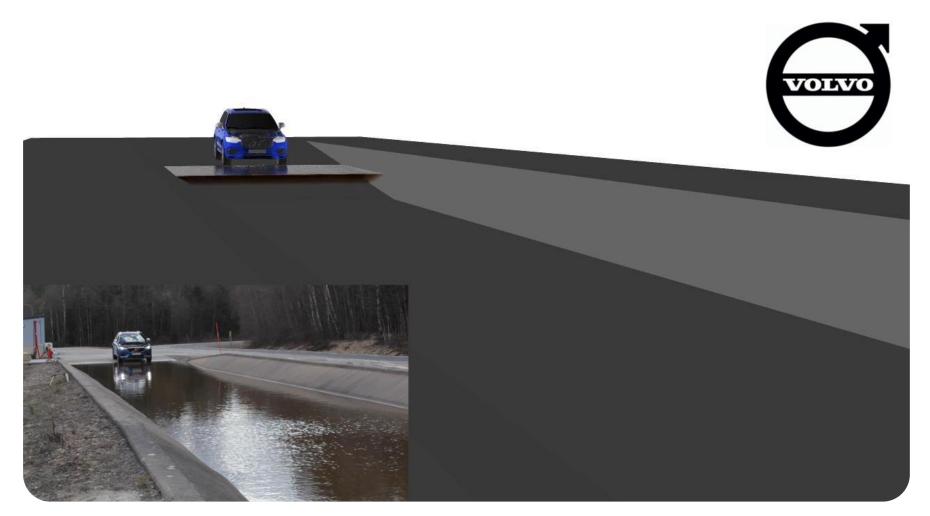
#### State-of-the-Art in 2014



Merkle & Partner Commercial CFD Product

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Current State-of-the-Art



Johan Idoffsson Chalmers University

Volvo Cars

PreonLab FIFTY2 Technology

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#### Evaluation





### **Computer Science in Simulation**

Efficiency	Usability	Reliability
Neighbor search	Boundary representation flexible, fast pre-proc.	Implicit formulations
Pressure solve large time steps	Pressure solver simple, intuitive setup	
Boundary handling large time steps	Monolithic solutions e.g. rigid-body solver	
•••	Pre- and Postprocessing	

## Further Applications

– Medicine

. . .

- Climate Research
- Entertainment

## Modeling - Simulation - Rendering

#### © Spellwork Pictures



Modeling

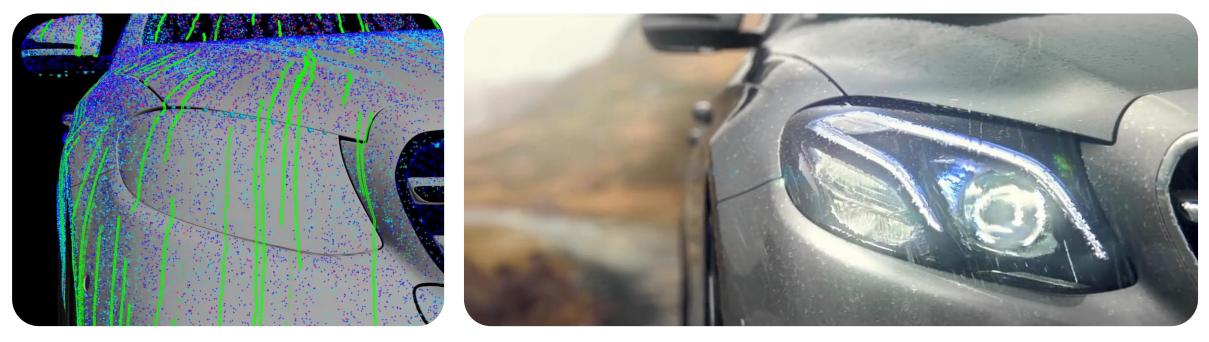


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## Modeling - Simulation - Rendering

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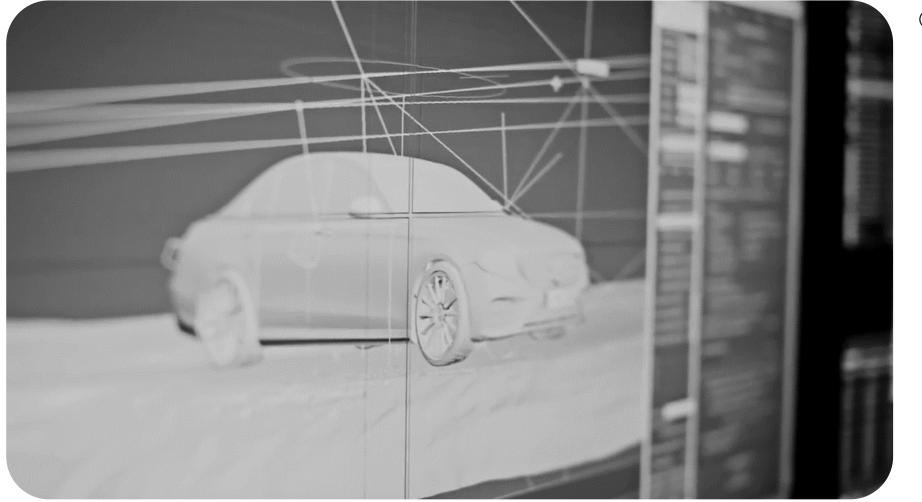


Simulation

Rendering



## Modeling - Simulation - Rendering



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#### Specialization Courses – Topics

Simulation
Particle Motion
Elastic Solids
Fluids (Particles and Grids)
Rigid Bodies
Contact

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#### Specialization Courses – Concepts

Rendering	Simulation	
Monte Carlo Integration	Smoothed Particle Hydrodynamics	
Monte Cano Integration	Shoothed Farticle Flydrodynamics	
Finite Element Modeling	Finite Differences	
Linear Systems		
Spatial Data Structures		
Real Time Graphics / High Performance Computing		

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## **Rendering Equation**

$$L(\boldsymbol{p} \to \boldsymbol{\omega}_o) = L_e(\boldsymbol{p} \to \boldsymbol{\omega}_o) + \int_{\Omega} f_r(\boldsymbol{p}, \boldsymbol{\omega}_i \leftrightarrow \boldsymbol{\omega}_o) L(\boldsymbol{p}' \leftarrow \boldsymbol{\omega}_i) \cos(\boldsymbol{\omega}_i, \boldsymbol{n}_p) \mathrm{d}\boldsymbol{\omega}_i$$

- Establishes relations between incident and exitant radiances
- Expresses the steady state of radiances in a scene
- Governs the computation of radiances from all scene points into all directions

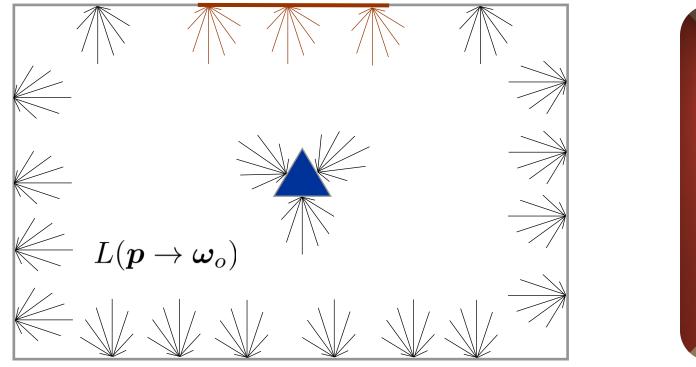


Akenine-Möller et al.

## Solving the Rendering Equation

- Exitant radiances from all scene points into all directions

 $L_e(oldsymbol{p}
ightarrowoldsymbol{\omega}_o)$ 

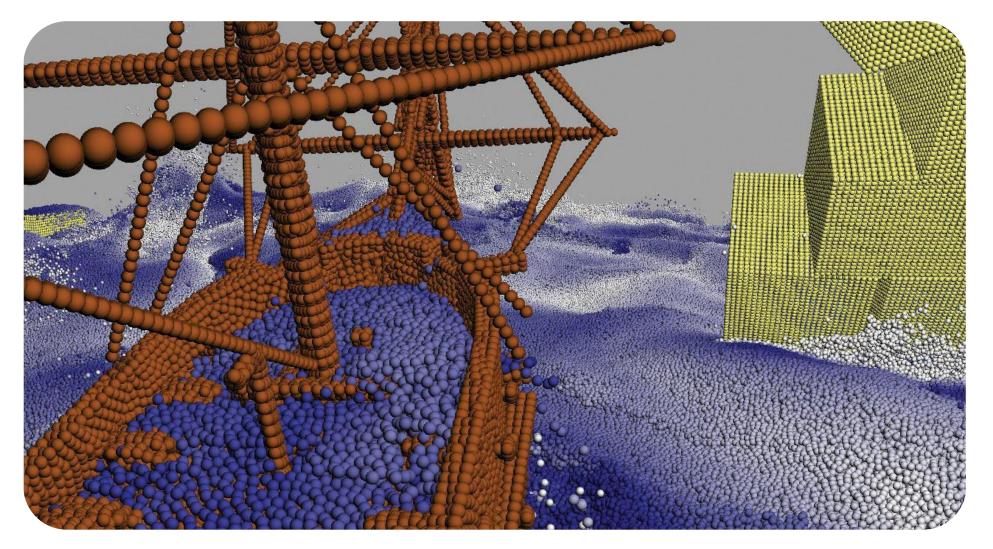




Cornell box

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#### **Particle Simulation**



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*Projects – Theses* 

Rendering Track	Simulation Track
Simple Raytracer	Simple Fluid Solver
Data Structures	Data Structures
Stochastic Raytracer	Incompressible SPH Solver

Features / Performance / Research

Please contact me per email two / three weeks before the semester starts.

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## Image Processing

- Slides, recordings, information on

- https://lmb.informatik.unifreiburg.de/lectures/image\_processing/
- First class on
  - Tuesday, June 13, 14:15

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