## MLS Pressure Boundaries for Divergence-Free and Viscous SPH Fluids - Appendix

Stefan Band

## 1 Mass of a boundary particle

Iterative solvers such as PCISPH [11], IISPH [5] or DFSPH [4] compute a pressure field p and apply pressure accelerations of the form

$$\boldsymbol{a}_{f}^{\mathrm{p}} = -\sum_{j} m_{j} \left( \frac{p_{f}}{\rho_{f}^{2}} + \frac{p_{j}}{\rho_{j}^{2}} \right) \boldsymbol{\nabla} W_{fj} - \sum_{b} m_{b} \left( \frac{p_{f}}{\rho_{f}^{2}} + \frac{p_{b}}{\rho_{b}^{2}} \right) \boldsymbol{\nabla} W_{ff_{b}}$$
(1)

to fluid particles f [3]. Here, j and b denote fluid and boundary neighbors of fluid particle f, respectively. Equation (1) requires a notion of mass  $m_b$  and density  $\rho_b$  at boundary particles b.

The mass  $m_b$  at a boundary particle *b* can be geometrically motivated from the boundary particle volume  $V_b$  [1, 10, 2], i.e. the mass  $m_b$  can be derived from the relation  $m_b = \rho_b V_b$ . Since the density  $\rho_b$  is typically set to the rest density of the adjacent fluid particle [1], i.e.

$$\rho_b = \rho_f \,, \tag{2}$$

the mass  $m_b$  of a boundary particle b can be computed as

$$m_b = \rho_f^0 V_b^0 \,, \tag{3}$$

where  $\rho_f^0$  denotes the rest density of fluid particle f and the rest volume  $V_b^0$  is [2]

$$V_b^0 = \frac{\gamma}{\sum_{b_b} W_{bb_b}} \,. \tag{4}$$

The computation of Eq. (4) only processes boundary neighbors  $b_b$  of a boundary particle b as the rest volume does not depend on possibly adjacent fluid particles [2]. As only one layer of boundary particles is used to represent the surface of the boundary [1], the coefficient  $\gamma$  accounts for an incomplete neighborhood. The coefficient depends on the choice of the SPH kernel function. For the cubic spline kernel [7] with a smoothing length of two times the particle size  $h, \gamma \approx 0.7$  [2]. This motivated by the fact that  $0.7 / \sum_{b_b} W_{bb_b} = h^3$  for boundary particles that are evenly sampled in a plane. See Fig. 1 for an illustration of the derivation.



Figure 1: Cross section of a boundary plane with color-coded SPH kernel weights. In 3D, red represents 31.8%, orange 8% and yellow 1.6% of the total kernel weight. Due to missing particle neighbors (crossed), the sum of kernel weights of the central particle is not 100% but  $1 \cdot 31.8\% + 4 \cdot 8\% + 4 \cdot 1.6\% = 70.2\%$ .

**Implementation** Employing Eqs. (2) to (4), the pressure acceleration of a fluid particle f, Eq. (1), can be computed as

$$\boldsymbol{a}_{f}^{\mathrm{p}} = -\sum_{j} m_{j} \left( \frac{p_{f}}{\rho_{f}^{2}} + \frac{p_{j}}{\rho_{j}^{2}} \right) \boldsymbol{\nabla} W_{fj} - \sum_{b} \rho_{f}^{0} V_{b}^{0} \left( \frac{p_{f}}{\rho_{f}^{2}} + \frac{p_{b}}{\rho_{f}^{2}} \right) \boldsymbol{\nabla} W_{fb} \,. \tag{5}$$

## 2 Pressure Extrapolation with MLS

The pressure  $p_b$  at boundary particle b is computed as

$$p_b = (1, \bar{x}_b, \bar{y}_b, \bar{z}_b)^{\mathrm{T}} \cdot \boldsymbol{c}_b , \qquad (6)$$

where  $\mathbf{c}_b = (\alpha_b, \beta_b, \gamma_b, \delta_b)^{\mathrm{T}}$  is a vector of unknown coefficients. The first parameter  $\alpha_b$  is the weighted average of the pressure values of fluid particles  $b_f$  adjacent to boundary particle b:

$$\alpha_b = \frac{\sum_{b_f} p_{b_f} V_{b_f} W_{bb_f}}{\sum_{b_f} V_{b_f} W_{bb_f}},\tag{7}$$

The other parameters  $\beta_b$ ,  $\gamma_b$  and  $\delta_b$  are obtained by solving

$$\begin{bmatrix} \beta_b \\ \gamma_b \\ \delta_b \end{bmatrix} = \left( \sum_{b_f} \begin{bmatrix} \bar{x}_{b_f}^2 & \bar{x}_{b_f} \bar{y}_{b_f} & \bar{x}_{b_f} \bar{z}_{b_f} \\ \bar{x}_{b_f} \bar{y}_{b_f} & \bar{y}_{b_f}^2 & \bar{y}_{b_f} \bar{z}_{b_f} \\ \bar{x}_{b_f} \bar{z}_{b_f} & \bar{y}_{b_f} \bar{z}_{b_f} & \bar{z}_{b_f}^2 \end{bmatrix} V_{b_f} W_{bb_f} \right)^{-1} \sum_{b_f} \begin{bmatrix} \bar{x}_{b_f} \\ \bar{y}_{b_f} \\ \bar{z}_{b_f} \end{bmatrix} p_{b_f} V_{b_f} W_{bb_f} .$$
(8)

**Implementation** In our experiments, we experienced issues with a singular matrix in Eq. (8) for boundary particles whose fluid neighbors are co-linear or

co-planar. In these cases, we follow [8] and use safe inversion via Singular Value Decomposition (SVD) [9] to avoid the problems with singular matrices. We use the SVD implementation of [6].

Also, we set  $\beta_b$ ,  $\gamma_b$  and  $\delta_b$  to zero if  $||\sum_{b_f} (\bar{x}_{b_f}, \bar{y}_{b_f}, \bar{z}_{b_f})^{\mathrm{T}} p_{b_f} V_{b_f} W_{bb_f}|| < \epsilon$ , where  $\epsilon$  is a small value, e.g.,  $10^{-5}$ . This results in a pressure value  $p_b = \alpha_b$ .

## References

- N. Akinci, M. Ihmsen, G. Akinci, B. Solenthaler, and M. Teschner. Versatile Rigid-fluid Coupling for Incompressible SPH. ACM Transactions on Graphics, 31(4):62:1–62:8, 2012.
- [2] S. Band, C. Gissler, M. Ihmsen, J. Cornelis, A. Peer, and M. Teschner. Pressure Boundaries for Implicit Incompressible SPH. ACM Transactions on Graphics, 37(2):14:1–14:11, 2018. Presented at SIGGRAPH 2018.
- [3] S. Band, C. Gissler, A. Peer, and M. Teschner. MLS Pressure Boundaries for Divergence-Free and Viscous SPH Fluids. *Computers & Graphics*, 76:37–46, 2018.
- [4] J. Bender and D. Koschier. Divergence-Free SPH for Incompressible and Viscous Fluids. *IEEE Transactions on Visualization and Computer Graphics*, 23(3):1193–1206, 2017.
- [5] M. Ihmsen, J. Cornelis, B. Solenthaler, C. Horvath, and M. Teschner. Implicit incompressible SPH. *IEEE Transactions on Visualization and Computer Graphics*, 20(3):426–435, 2014.
- [6] Jacob, Benoît and Guennebaud, Gaël. Eigen. https://eigen.tuxfamily. org, 2018.
- [7] J. J. Monaghan. Smoothed Particle Hydrodynamics. Reports on Progress in Physics, 68(8):1703, 2005.
- [8] M. Müller, R. Keiser, A. Nealen, M. Pauly, M. H. Gross, and M. Alexa. Point Based Animation of Elastic, Plastic and Melting Objects. In ACM SIGGRAPH/Eurographics Symposium on Computer Animation, pages 141– 151. Eurographics Association, 2004.
- [9] W. H. Press, S. A. Teukolsky, W. T. Vetterling, and B. P. Flannery. Numerical Recipes 3rd Edition: The Art of Scientific Computing. Cambridge University Press, New York, NY, USA, 3 edition, 2007.
- [10] S. Rosswog. SPH Methods in the Modelling of Compact Objects. Living Reviews in Computational Astrophysics, 1(1), 2015.
- [11] B. Solenthaler and R. Pajarola. Predictive-corrective Incompressible SPH. ACM Transactions on Graphics, 28(3):40:1–40:6, 2009.