# MLS Pressure Boundaries for Divergence-Free and Viscous SPH Fluids - Appendix 

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## 1 Mass of a boundary particle

Iterative solvers such as PCISPH [11, IISPH [5] or DFSPH 4 compute a pressure field $p$ and apply pressure accelerations of the form

$$
\begin{equation*}
\boldsymbol{a}_{f}^{\mathrm{p}}=-\sum_{j} m_{j}\left(\frac{p_{f}}{\rho_{f}^{2}}+\frac{p_{j}}{\rho_{j}^{2}}\right) \nabla W_{f j}-\sum_{b} m_{b}\left(\frac{p_{f}}{\rho_{f}^{2}}+\frac{p_{b}}{\rho_{b}^{2}}\right) \nabla W_{f f_{b}} \tag{1}
\end{equation*}
$$

to fluid particles $f$ [3]. Here, $j$ and $b$ denote fluid and boundary neighbors of fluid particle $f$, respectively. Equation (1) requires a notion of mass $m_{b}$ and density $\rho_{b}$ at boundary particles $b$.
The mass $m_{b}$ at a boundary particle $b$ can be geometrically motivated from the boundary particle volume $V_{b}$ [1, 10, 2], i.e. the mass $m_{b}$ can be derived from the relation $m_{b}=\rho_{b} V_{b}$. Since the density $\rho_{b}$ is typically set to the rest density of the adjacent fluid particle [1], i.e.

$$
\begin{equation*}
\rho_{b}=\rho_{f} \tag{2}
\end{equation*}
$$

the mass $m_{b}$ of a boundary particle $b$ can be computed as

$$
\begin{equation*}
m_{b}=\rho_{f}^{0} V_{b}^{0} \tag{3}
\end{equation*}
$$

where $\rho_{f}^{0}$ denotes the rest density of fluid particle $f$ and the rest volume $V_{b}^{0}$ is [2]

$$
\begin{equation*}
V_{b}^{0}=\frac{\gamma}{\sum_{b_{b}} W_{b b_{b}}} \tag{4}
\end{equation*}
$$

The computation of Eq. (4) only processes boundary neighbors $b_{b}$ of a boundary particle $b$ as the rest volume does not depend on possibly adjacent fluid particles [2]. As only one layer of boundary particles is used to represent the surface of the boundary [1], the coefficient $\gamma$ accounts for an incomplete neighborhood. The coefficient depends on the choice of the SPH kernel function. For the cubic spline kernel [7] with a smoothing length of two times the particle size $h, \gamma \approx 0.7$ [2]. This motivated by the fact that $0.7 / \sum_{b_{b}} W_{b b_{b}}=h^{3}$ for boundary particles that are evenly sampled in a plane. See Fig. 1 for an illustration of the derivation.


Figure 1: Cross section of a boundary plane with color-coded SPH kernel weights. In 3D, red represents $31.8 \%$, orange $8 \%$ and yellow $1.6 \%$ of the total kernel weight. Due to missing particle neighbors (crossed), the sum of kernel weights of the central particle is not $100 \%$ but $1 \cdot 31.8 \%+4 \cdot 8 \%+4 \cdot 1.6 \%=70.2 \%$.

Implementation Employing Eqs. (2) to (4), the pressure acceleration of a fluid particle $f$, Eq. (1), can be computed as

$$
\begin{equation*}
\boldsymbol{a}_{f}^{\mathrm{p}}=-\sum_{j} m_{j}\left(\frac{p_{f}}{\rho_{f}^{2}}+\frac{p_{j}}{\rho_{j}^{2}}\right) \nabla W_{f j}-\sum_{b} \rho_{f}^{0} V_{b}^{0}\left(\frac{p_{f}}{\rho_{f}^{2}}+\frac{p_{b}}{\rho_{f}^{2}}\right) \nabla W_{f b} \tag{5}
\end{equation*}
$$

## 2 Pressure Extrapolation with MLS

The pressure $p_{b}$ at boundary particle $b$ is computed as

$$
\begin{equation*}
p_{b}=\left(1, \bar{x}_{b}, \bar{y}_{b}, \bar{z}_{b}\right)^{\mathrm{T}} \cdot \boldsymbol{c}_{b} \tag{6}
\end{equation*}
$$

where $\boldsymbol{c}_{b}=\left(\alpha_{b}, \beta_{b}, \gamma_{b}, \delta_{b}\right)^{\mathrm{T}}$ is a vector of unknown coefficients. The first parameter $\alpha_{b}$ is the weighted average of the pressure values of fluid particles $b_{f}$ adjacent to boundary particle $b$ :

$$
\begin{equation*}
\alpha_{b}=\frac{\sum_{b_{f}} p_{b_{f}} V_{b_{f}} W_{b b_{f}}}{\sum_{b_{f}} V_{b_{f}} W_{b b_{f}}} \tag{7}
\end{equation*}
$$

The other parameters $\beta_{b}, \gamma_{b}$ and $\delta_{b}$ are obtained by solving

$$
\begin{array}{r}
{\left[\begin{array}{c}
\beta_{b} \\
\gamma_{b} \\
\delta_{b}
\end{array}\right]=\left(\sum_{b_{f}}\left[\begin{array}{ccc}
\bar{x}_{b_{f}}^{2} & \bar{x}_{b_{f}} \bar{y}_{b_{f}} & \bar{x}_{b_{f}} \bar{z}_{b_{f}} \\
\bar{x}_{b_{f}} \bar{y}_{b_{f}} & \bar{y}_{b_{f_{f}}}^{2} & \bar{y}_{b_{f}} \bar{z}_{b_{f}} \\
\bar{x}_{b_{f}} \bar{z}_{b_{f}} & \bar{y}_{b_{f}} \bar{z}_{b_{f}} & \bar{z}_{b_{f}}^{2}
\end{array}\right] V_{b_{f}} W_{b b_{f}}\right)^{-1}} \\
\sum_{b_{f}}\left[\begin{array}{c}
\bar{x}_{b_{f}} \\
\bar{y}_{b_{f}} \\
\bar{z}_{b_{f}}
\end{array}\right] p_{b_{f}} V_{b_{f}} W_{b b_{f}} . \tag{8}
\end{array}
$$

Implementation In our experiments, we experienced issues with a singular matrix in Eq. (8) for boundary particles whose fluid neighbors are co-linear or
co-planar. In these cases, we follow [8 and use safe inversion via Singular Value Decomposition (SVD) [9 to avoid the problems with singular matrices. We use the SVD implementation of [6].
Also, we set $\beta_{b}, \gamma_{b}$ and $\delta_{b}$ to zero if $\left\|\sum_{b_{f}}\left(\bar{x}_{b_{f}}, \bar{y}_{b_{f}}, \bar{z}_{b_{f}}\right)^{\mathrm{T}} p_{b_{f}} V_{b_{f}} W_{b b_{f}}\right\|<\epsilon$, where $\epsilon$ is a small value, e.g., $10^{-5}$. This results in a pressure value $p_{b}=\alpha_{b}$.

## References

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